

# A Hardy type inequality for $W_0^{2,1}(\Omega)$ functions

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## Abstract

We consider functions  $u \in W_0^{2,1}(\Omega)$ , where  $\Omega \subset \mathbb{R}^N$  is a smooth bounded domain. We prove that  $\frac{u(x)}{d(x)} \in W_0^{1,1}(\Omega)$  with

$$\left\| \nabla \left( \frac{u(x)}{d(x)} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{2,1}(\Omega)},$$

where  $d$  is a smooth positive function which coincides with  $\text{dist}(x, \partial\Omega)$  near  $\partial\Omega$  and  $C$  is a constant depending only on  $\Omega$ .

## Résumé

**Une inégalité de type Hardy pour les fonctions de  $W_0^{2,1}(\Omega)$ .** Nous considérons des fonctions  $u \in W_0^{2,1}(\Omega)$ , où  $\Omega \subset \mathbb{R}^N$  est un domaine régulier borné. Nous prouvons que  $\frac{u(x)}{d(x)} \in W_0^{1,1}(\Omega)$  avec

$$\left\| \nabla \left( \frac{u(x)}{d(x)} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{2,1}(\Omega)},$$

où  $d$  est une fonction régulière positive qui coïncide avec  $\text{dist}(x, \partial\Omega)$  près de  $\partial\Omega$  et  $C$  est une constante ne dépendant que de  $\Omega$ .

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## 1. Introduction

In [4], the following one dimensional Hardy type inequality was proven (see Theorem 1.2 in [4]): Suppose that  $u \in W^{2,1}(0, 1)$  satisfies  $u(0) = u'(0) = 0$ , then  $\frac{u(x)}{x} \in W^{1,1}(0, 1)$  with  $\frac{u(x)}{x} \Big|_0 = 0$  and

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$$\left\| \left( \frac{u(x)}{x} \right)' \right\|_{L^1(0,1)} \leq \|u''\|_{L^1(0,1)}. \quad (1)$$

As explained [4], this inequality is somehow unexpected because one can construct a function  $u \in W^{2,1}(0,1)$  such that  $u(0) = u'(0) = 0$  and that neither  $\frac{u'(x)}{x}$  nor  $\frac{u(x)}{x^2}$  belong to  $L^1(0,1)$ ; however, as (1) shows, for such function  $u$ , the difference  $\frac{u'(x)}{x} - \frac{u(x)}{x^2} = \left( \frac{u(x)}{x} \right)'$  is in fact an  $L^1$  function, reflecting a “magical” cancelation of the non-integrable terms.

The purpose of this work is to present the complete analog of the estimate (1) in dimension  $N \geq 2$ . We have the following:

**Theorem 1.1** *Let  $\Omega$  be a bounded domain in  $\mathbb{R}^N$  with smooth boundary  $\partial\Omega$ . Given  $x \in \Omega$ , we denote by  $\delta(x)$  the distance from  $x$  to the boundary  $\partial\Omega$ . Let  $d : \Omega \rightarrow (0, +\infty)$  be a smooth function such that  $d(x) = \delta(x)$  near  $\partial\Omega$ . Then for every  $u \in W_0^{2,1}(\Omega)$ , we have  $\frac{u(x)}{d(x)} \in W_0^{1,1}(\Omega)$  with*

$$\left\| \nabla \left( \frac{u(x)}{d(x)} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{2,1}(\Omega)}, \quad (2)$$

where  $C > 0$  is a constant depending only on  $\Omega$ .

In Section 2 we present the notation and in Section 3 we sketch the proof of Theorem 1.1.

## 2. Notation and preliminaries

Throughout this work, we denote  $\tilde{y} = (y_1, \dots, y_{N-1})$ ,  $\mathbb{R}_+^N := \{y_N > 0\}$ , and  $B_r^N := \{y \in \mathbb{R}^N : |y| < r\}$ ;  $\Omega \subset \mathbb{R}^N$  is always a bounded domain with smooth boundary  $\partial\Omega$ ; we denote by  $\delta(x) := \text{dist}(x, \partial\Omega)$ . Using Lemma 14.16 in [6], one can construct a smooth change of coordinates  $\Phi : B_r^{N-1} \times (-\epsilon_0, \epsilon_0) \rightarrow \mathbb{R}^N$ , where

$$\Phi(\tilde{y}, t) := \tilde{\Phi}(\tilde{y}) + y_N \cdot \nu_{\partial\Omega}(\tilde{\Phi}(\tilde{y})), \quad (3)$$

and  $\tilde{\Phi} : B_r^{N-1} \rightarrow \mathcal{V}(\tilde{x}_0)$  is a smooth coordinate chart at  $\tilde{x}_0 \in \partial\Omega$ . If we denote

$$\mathcal{N}(\tilde{x}_0) := \Phi(B_r^{N-1} \times (-\epsilon_0, \epsilon_0)), \quad (4)$$

then the map  $\Phi|_{B_r^{N-1} \times (0, \epsilon_0)}$  is a diffeomorphism and

$$\mathcal{N}_+(\tilde{x}_0) := \{x \in \Omega_{\epsilon_0} : y_x \in \mathcal{V}(\tilde{x}_0)\} = \Phi(B_r^{N-1} \times (0, \epsilon_0)). \quad (5)$$

This type of coordinates are sometimes called *flow coordinates* (see e.g. [3] and [7]). From now on,  $C > 0$  will denote a constant only depending on  $\Omega$ .

## 3. The proof of the Theorem

The key ingredient in the proof is the following lemma

**Lemma 3.1** *Suppose  $u \in C_0^\infty(\mathbb{R}_+^N)$ . Then for all  $i = 1, \dots, N$  we have*

$$\left\| \partial_i \left( \frac{u(y)}{y_N} \right) \right\|_{L^1(\mathbb{R}_+^N)} \leq C \|u\|_{W^{2,1}(\mathbb{R}_+^N)}.$$

*Proof.* We first notice that when  $i = N$ , the result is essentially contained in the proof of Theorem 1.2 of [4] when  $j = 0$ ,  $k = 1$  and  $m = 2$ . We refer the reader to [4] for the details. When  $1 \leq i \leq N - 1$ , define  $v(x) = u(\Psi(x))$  where  $\Psi(x_1, \dots, x_i, \dots, x_N) = (x_1, \dots, x_i + x_N, \dots, x_N)$ . We have

$$\frac{1}{x_N} \frac{\partial u}{\partial y_i}(\Psi(x)) = \frac{\partial}{\partial x_N} \left( \frac{v(x)}{x_N} \right) - \frac{\partial}{\partial y_N} \left( \frac{u(y)}{y_N} \right) \Big|_{y=\Psi(x)},$$

hence the estimate is reduced to the estimate for  $i = N$ . □

Next we use Lemma 3.1 together with the straightening of the boundary given by  $\Phi$  in Section 2 to obtain

**Lemma 3.2** *Let  $\tilde{x}_0 \in \partial\Omega$  and  $\mathcal{N}_+(\tilde{x}_0)$  be given by (5). Suppose  $u \in C_0^\infty(\mathcal{N}_+(\tilde{x}_0))$ . Then for all  $i = 1, \dots, N$  we have*

$$\left\| \partial_i \left( \frac{u(x)}{\delta(x)} \right) \right\|_{L^1(\mathcal{N}_+(\tilde{x}_0))} \leq C \|u\|_{W^{2,1}(\mathcal{N}_+(\tilde{x}_0))}.$$

*Proof.* Let  $v(\tilde{y}, y_N) = u(\Phi(\tilde{y}, y_N))$ . Using that  $\Phi$  is a smooth diffeomorphism gives

$$\int_{\mathcal{N}_+(\tilde{x}_0)} \left| \partial_i \left( \frac{u(x)}{\delta(x)} \right) \right| dx \leq C \sum_{j=1}^N \int_{B_r^{N-1}} \int_0^{\epsilon_0} \left| \partial_j \left( \frac{v(\tilde{y}, y_N)}{y_N} \right) \right| dy_N d\tilde{y}. \quad (6)$$

Since  $v \in C_0^\infty(B_r^{N-1} \times (0, \epsilon_0)) \subset C_0^\infty(\mathbb{R}_+^N)$ , we can apply Lemma 3.1 and obtain

$$\int_{B_r^{N-1}} \int_0^{\epsilon_0} \left| \partial_j \left( \frac{v(\tilde{y}, y_N)}{y_N} \right) \right| dy_N d\tilde{y} \leq C \|v\|_{W^{2,1}(B_r^{N-1} \times (0, \epsilon_0))}.$$

Notice that by the chain rule and the fact that  $\Phi$  is a smooth diffeomorphism, we get

$$\|v\|_{W^{2,1}(B_r^{N-1} \times (0, \epsilon_0))} \leq C \|u\|_{W^{2,1}(\mathcal{N}_+(\tilde{x}_0))}.$$

□

*Proof of Theorem 1.1.* Applying Lemma 3.2 and a partition of unity (see e.g. Lemma 9.3 in [2] and Theorem 3.15 in [1]), one can obtain that

$$\left\| \partial_i \left( \frac{u(x)}{\delta(x)^{m-1}} \right) \right\|_{L^1(\Omega)} \leq C \|u\|_{W^{m,1}(\Omega)}.$$

for  $u \in C_0^\infty(\Omega)$  and  $i = 1, \dots, N$ . Then one can complete the proof of Theorem 1.1 using a standard density argument. □

*Remark 1* *In fact, we have a full generalization of Theorem 1.1 for functions in  $W_0^{m,1}(\Omega)$  for all the integers  $m \geq 2$ , which is presented in [5].*

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